On Optimal t-distributed Stochastic Neighbor Embeddings

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Background: t-distributed stochastic neighbor embedding (t-SNE), created by [MHo8, HSo2], is a nonlinear dimensionality reduction algorithm, provably good at visualizing cluster structure in high-dimensional data [AHK21, LS19]. **Problem:** Gradient-based optimization (practical implementation) only shows

us local minima of the t-SNE objective.

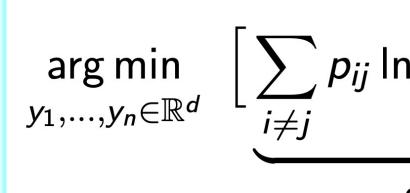
Goal: What can we say about *global minima* or the t-SNE objective function?

t-SNE formulation and pathological cases...

We think of t-SNE as a graph embedding problem (more general than its original formulation as a metric embedding).

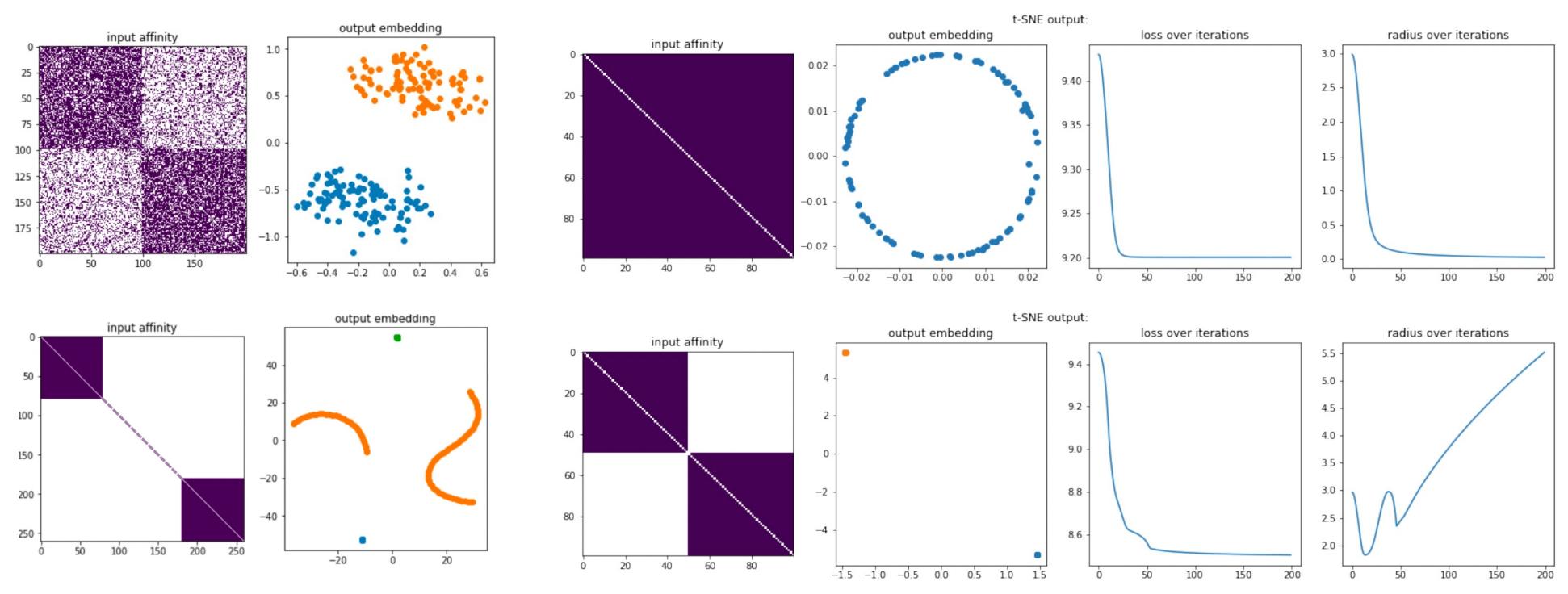
- Given: an N×N "affinity" matrix (P_{ii}) with zero diagonal, symmetric, non-negative, and all entries sum to 1.
- Construct low-dimensional points (y_i) and a corresponding affinity matrix (Q_{ii}) , computed as follows
- Find (y_i) which minimizes the Kullback-Leibler divergence (relative entropy) of (P_{ii}) with respect to (Q_{ii}) .

An (new) advantageous way of rewriting our loss:



Observation 1: Non-metric embeddable graphs such as stochastic block models and "clique-path" graphs are still well-clustered by t-SNE. **Observation 2:** However, this generalization admits simple examples cases where: • The optimal embedding is **trivial**

• No optimal embedding exists (i.e. the infimum of the objective isn't attained)



t-SNE on non-metric graphs. Capable of clustering planted partition graphs with p as low as 0.55

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$$Q_{ij} = rac{(1+||y_i-y_j||^2)^{-1}}{\sum_{k
eq I} (1+||y_k-y_I||^2)^{-1}}$$

$$\mathit{KL}(P||Q) = \sum_{i=1}^{N}\sum_{j=1}^{N}P_{ij}\ln(P_{ij}/Q_{ij})$$

$$n(1 + ||y_i - y_j||^2) + ln\left(\sum_{i \neq j} \frac{1}{1 + ||y_i - y_j||^2}\right)$$

contraction

repulsion

Illustration of two "pathological" cases of the t-SNE embedding, and how gradient descent optimization does not converge but rather contracts (top) and expands (bottom) indefinitely.

[CM22] established a rigorous connection between gradient-optimized t-SNE and spectral clustering. We build upon this connection, showing that the t-SNE objective, in low-diameter regimes, is approximately equal to the objective of Laplacian eigenmaps, a spectral method.

Theorem 10 (Approximate Spectral Clustering). Let $y = (y_1, ..., y_n) \in \mathbb{R}^{n \times 1}$ and a modified (but still equivalent for optimization purposes) t-SNE objective function $L_P(\mathbf{y}) =$ $KL(P||Q(\boldsymbol{y})) - H(P) - \ln(n^2 - n)$. If $diam(\boldsymbol{y}) \coloneqq d_{\boldsymbol{y}} < 1$, then:

where $L(\cdot)$ is the graph Laplacian of an $n \times n$ matrix and $H_n = \frac{1}{n^2 - n} (\mathbf{1}\mathbf{1}^T - I_n)$.

The proof is simple and involves mostly Taylor expansions on the loss function. It is relevant because the canonical implementation of t-SNE is in a small radius of [0.01,0.01]²,

A slight symmetry, as an artifact of normalization

We say the loss function has a *symmetry* if a non-identity transformation of embedding leaves the loss value the same. We found an infinite family of symmetries.

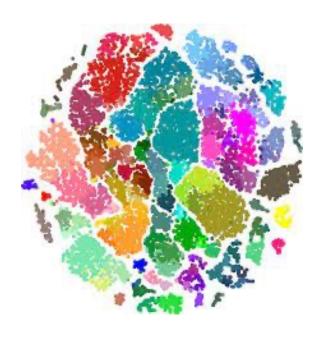
It is easy to find a non-identity transformation of the distance matrix which preserves the objective. The hard part of the proof is showing that this transformation of the distances is still Euclidean-embeddable. This involves the use of Gram matrices and some topological reasoning about the positive-semidefinite cone.

We prove that a P matrix with non-zero off-diagonal entries will always yield an optimal t-SNE embedding. Furthermore, we find that this optimal embedding will occur within a finite radius dependent on the number of points *n* and the smallest off-diagonal entry in P.

where $L_P(Y^*)$

This bound is likely not tight. In well-clustered settings, can show a much tighter n² dependence.

Works Cited:



Low-diameter t-SNE approximates Laplacian Eigenmaps: A new demonstration

$$\left| oldsymbol{y}^T L(P - H_n) oldsymbol{y} - L_P(oldsymbol{y})
ight| = O(n^2 d_{oldsymbol{y}}^4)$$

Theorem 1. For almost every $(y_1, ..., y_n) = Y \in \mathbb{R}^{dn}$, there exists an $\epsilon > 0$ and an infinite family of embeddings $\{Y_{\alpha}\}_{\alpha \in \mathcal{A}} \subset \mathbb{R}^{dn}$ such that:

 $||D(Y) - D(Y_{\alpha})||_{\infty} \in (0, \epsilon)$ and $L_P(Y) = L_P(Y_{\alpha}) \quad \forall \alpha \in \mathcal{A}$

where D(Y) is the matrix of squared distances, $[D(Y)]_{ij} = ||y_i - y_j||^2$.

Diameter bound and open questions

Proposition 7 (Diameter Bound). Given a P matrix with $\min_{i\neq j} P_{ij} \geq \frac{1}{Cn^2}$ for $C \in \mathbb{R}_{>0}$, there exists an optimal embedding Y^* with diameter $O(n^{n/c})$. Specifically:

$$\exists Y^* \in \mathbb{R}^{dn} \ s.t. \quad \max_{y,y' \in Y^*} ||y - y'|| \le 2n^{nC}$$

$$\leq L_P(Y)$$
 for all $Y \in \mathbb{R}^{dn}$.

Remaining questions are centered on the **hardness and approximability of t-SNE**. Is t-SNE optimization NP-hard? Perhaps reduce from NAE-3SAT^{*} or multi-terminal cuts? Can we develop a poly-time approximation scheme (PTAS) for t-SNE, in a similar vein as [DHKLU21]'s PTAS for multi-dimensional scaling? The crucial first step towards this is <u>a tighter</u> <u>diameter bound</u>—this would allow us to efficiently discretize the input space and turn this continuous problem into a discrete one, upon which we can apply greedy methods.

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