



t-SNE's spectral regime

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Outline of the Talk

- 1. Introduction to t-SNE
- 2. Introduction to Spectral Clustering
- 3. Cai and Ma (2022): the connection

Dimensionality Reduction

High dimensional data is everywhere

- Images (#pixels)
- Language (#vocabulary)
- Single-cell transcriptomics (#genes)

Oftentimes, it has low-dimensional **intrinsic structure** (e.g. a *manifold*).

Problem: Find a map into a lower-dimensional space, which preserves "information/structure"



The t-SNE approach (van der Maaten 2007)

- 1. Start with $\mathcal{X} = \{x_1, ..., x_n\} \subset \mathbb{R}^d$.
- 2. Randomly initialize the corresponding low-dimensional representations ("embeddings") $\mathcal{Y} = \{y_1, ..., y_n\} \subset \mathbb{R}^2$.
- 3. Iteratively update the $\mathcal Y$ embeddings, to match the local structure of $\mathcal X$.



How do we characterize "structure"?

Affinity matrix P associated with X.

For i
eq j, define

$$p_{j|i} = rac{\exp(-\|\mathbf{x}_i - \mathbf{x}_j\|^2/2\sigma_i^2)}{\sum_{k
eq i}\exp(-\|\mathbf{x}_i - \mathbf{x}_k\|^2/2\sigma_i^2)} \qquad p_{ij} = rac{p_{j|i} + p_{i|j}}{2N}$$

Gaussian distribution

Affinity matrix **Q** associated with **Y**.

$$q_{ij} = rac{(1+\|\mathbf{y}_i-\mathbf{y}_j\|^2)^{-1}}{\sum_k \sum_{l
eq k} (1+\|\mathbf{y}_k-\mathbf{y}_l\|^2)^{-1}}$$

Cauchy (Student-T) distribution

Cost Function and Updates

P and Q are discrete probability distributions

We compute their "distance"

$$\mathrm{KL}\left(P \parallel Q
ight) = \sum_{i
eq j} p_{ij} \log rac{p_{ij}}{q_{ij}}$$

We update the embeddings according to gradient descent.

$$\frac{\partial KL(P||Q)}{\partial y_i} = 4 \sum_{j \neq i}^n \frac{(\alpha p_{ij} - q_{ij})(y_i - y_j)}{(1 + ||y_i - y_j||^2)}$$

(alpha is the "early exaggeration" parameter. Helps experimentally.)

"Dynamical Systems Interpretation"

$$\begin{aligned} \frac{dC}{dy_i} &= 4 \sum_{j=1, j \neq i}^n (p_{ij} - q_{ij})(1 + ||y_i - y_j||^2)^{-1}(y_i - y_j) \\ &= 4 \sum_{j=1, j \neq i}^n (p_{ij} - q_{ij})q_{ij}Z(y_i - y_j) \\ &= 4 \Big(\sum_{j \neq i} p_{ij}q_{ij}Z(y_i - y_j) - \sum_{j \neq i} q_{ij}^2Z(y_i - y_j) \Big) \\ &= 4 (F_{attraction} + F_{repulsion}) \end{aligned}$$



Spectral Dimensionality Reduction

- 1. Start with $\mathcal{X} = \{x_1, ..., x_n\} \in \mathcal{M}_{d \times n}$.
- Construct an adjacency matrix A_X corresponding to some kind "similarity graph" on X (like k-nearest neighbors, or affinity matrix)
 Compute the eigenvectors of L(A_X), the graph Laplacian.
 Construct Y = {y₁,..., y_n} ∈ M_{k×n}, where the rows are the k lowest eigenvectors.

Example

- e.g. 2-nearest neighbors
- $\mathcal{X} = \{(1,3), (1,1), (2,0), (-2,-2), (-3,-3), (-5,0)\}:$





"Block matrix," indicative of cluster structure

We want to use spectral decomposition to detect clusters of points.

The Graph Laplacian

The heart of **spectral graph theory**; many nice properties

- Analogous to the Laplace operator in calc($\nabla^2 s$:

Operates on a graph G.

- The adjacency matrix records whether
- The degree matrix (diagonal) records how many edges on a given node

Formula: $\mathbf{L} = \mathbf{D} - \mathbf{A}$

Cai and Ma (2022): the spectral regime

- 1. **Rewrite** the t-SNE gradient update in matrix form.
- 2. Find conditions for when the update matrix is roughly constant. This is a **power iteration.**
- 3. Show that the power iteration converges.

1. $y_k = A_k y_{k-1}$ 2. $A_k = A$. Therefore $y_k = A^k y_0$. 3. $\lim_{k\to\infty} A^k y_0$?

Cai and Ma (2022)

Rewrite the t-SNE update.

$$S_{ij}^{(k)}(\alpha) = rac{lpha p_{ij} - q_{ij}^{(k)}}{1 + ||y_i^{(k)} - y_j^{(k)}||^2}$$

$$y_i^{(k+1)} = y_i^{(k)} + h \sum_{1 \le j \le n, j \ne i} (y_j^{(k)} - y_i^{(k)}) S_{ij}^{(k)}(\alpha), \quad i = 1, ..., n,$$

Look at the row space of the embedding.

$$oldsymbol{y}_{\ell}^{(k+1)} = [\mathbf{I}_n - h \mathbf{L}(\mathbf{S}_{\alpha}^{(k)})] oldsymbol{y}_{\ell}^{(k)}, \quad \ell = 1, 2,$$

The path to POWER ITERATIONS

$$oldsymbol{y}_{\ell}^{(k+1)} = [\mathbf{I}_n - h\mathbf{L}(\mathbf{S}_{\alpha}^{(k)})]oldsymbol{y}_{\ell}^{(k)}, \quad \ell = 1, 2,$$
 1) Original.
 $oldsymbol{y}_{\ell}^{(k+1)} \approx [\mathbf{I}_n - h\mathbf{L}(lpha \mathbf{P} - \mathbf{H}_n)]oldsymbol{y}_{\ell}^{(k)}, \quad \ell = 1, 2,$ 2) Roughly constant adjacency matrix $oldsymbol{y}_{\ell}^{(k+1)} \approx [\mathbf{I}_n - h\mathbf{L}(lpha \mathbf{P} - \mathbf{H}_n)]^k oldsymbol{y}_{\ell}^{(0)}.$ 3) Power iterations

$$\mathbf{H}_n = rac{1}{n(n-1)} (\mathbf{1}_n \mathbf{1}_n^\top - \mathbf{I}_n),$$

Question: Where do these power iterations lead?

Answer: Power iterations lead to the null space of L(P)!

Let R be the dimension of the null space of L(P)

Let U be a n by R matrix, whose columns are the orthogonal basis for the null space of L(P).

$$\boldsymbol{y}_{\ell}^{(k)} \approx \mathbf{U} \mathbf{U}^{\top} \boldsymbol{y}_{\ell}^{(0)}, \quad \ell \in [2].$$

The Laplacian null-space records clusters...

Consider well-clustered data (P effectively a block matrix!)

Proposition 6 (Laplacian null space) Suppose $\mathbf{A} \in \mathbb{R}^{n \times n}$ is symmetric and well conditioned. Then the smallest eigenvalue of the Laplacian $\mathbf{L}(\mathbf{A})$ is 0 and has multiplicity R, and the associated eigen subspace is spanned by $\{\boldsymbol{\theta}_1, ..., \boldsymbol{\theta}_R\}$ where for each $r \in \{1, ..., R\}$,

 $[\boldsymbol{\theta}_r]_j = \left\{ egin{array}{ccc} 1/\sqrt{n_r} & \mbox{if the j-th node belongs to the r-th component} \\ 0 & \mbox{otherwise} \end{array}
ight.,$

and n_r is the number of nodes in the r-th connected component. In particular, up to possible permutation of coordinates, any vector **u** in the null space of $\mathbf{L}(\mathbf{A})$ can be expressed as

$$\mathbf{u} = \frac{a_1}{\sqrt{n_1}} \begin{bmatrix} \mathbf{l}_{n_1} \\ \mathbf{0} \\ \vdots \\ \mathbf{0} \end{bmatrix} + \frac{a_2}{\sqrt{n_2}} \begin{bmatrix} \mathbf{0} \\ \mathbf{l}_{n_2} \\ \vdots \\ \mathbf{0} \end{bmatrix} + \dots + \frac{a_R}{\sqrt{n_R}} \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \vdots \\ \mathbf{l}_{n_R} \end{bmatrix},$$
(17)

for some $a_1, ..., a_R \in \mathbb{R}$.

Hence, under certain conditions, we know exactly where the embeddings are going...

Theorem 7 (Implicit clustering and early stopping) Suppose the similarity \mathbf{P} and the tuning parameters (α, h, k) satisfy (T1.D) and (T2.D), and the initialization satisfies (I1) and (I2). Then there exists some permutation matrix $O \in \mathbb{R}^{n \times n}$ such that, for $\ell \in [2]$,

$$\lim_{k,n)\to\infty} \frac{\|\boldsymbol{y}_{\ell}^{(k)} - O\boldsymbol{z}_{\ell}\|_2}{\|\boldsymbol{y}_{\ell}^{(0)}\|_2} = 0,$$
(18)

where

$$\mathbf{z}_{\ell} = (\underbrace{z_{\ell 1}, \dots, z_{\ell 1}}_{n_1}, \underbrace{z_{\ell 2}, \dots, z_{\ell 2}}_{n_2}, \dots, \underbrace{z_{\ell R}, \dots, z_{\ell R}}_{n_R})^{\top} \in \mathbb{R}^n,$$
(19)

and $z_{\ell r} = \boldsymbol{\theta}_r^{\top} \boldsymbol{y}_{\ell}^{(0)} / \sqrt{n_r}$ for $r \in [R]$.

Conclusion

t-SNE is powerful but not very well-understood

Spectral clustering is well-understood

Cai and Ma show a deep connection between t-SNE and spectral clustering.

Question (Linderman): Is t-SNE just spectral clustering is disguise? It seems to perform better, so there should be more to this story...

Works Cited

Cai and Ma, *Theoretical Foundations of t-SNE for Visualizing High-Dimensional Clustered Data* (2022)

Van der Maaten and Hinton, Visualizing Data using t-SNE (2008)

Ulrike von Luxburg, A Tutorial on Spectral Graph Theory (2007)

Problem with SNE: "crowding problem"

SNE suffers from the "crowding problem": The area of the 2D map that is available to accommodate moderately distant data points will not be large enough compared with the area available to accommodate nearby data points.



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Ziyuan Zhong (Columbia University) t-SNE July 4, 2018 14 / 72

Unified Framework of Linear Dimensionality Reduction

Discussion

We can put most linear dimensionality reduction algorithms in a unified framework. Essentially, they are all special cases of Kernel-PCA.

- PCA: $K = X^T X$ (Linear Kernel).
- Classical-MDS: $K = \frac{-1}{2} H D^{Euclidean} H$ where H is the centering matrix.
- Isomap: $K = \frac{-1}{2} H D^{Geodesic} H$.
- LLE: once W is learned, $K = M^{-1}$ or $K = (\lambda_{max}I M)$, where $M = (I W)(I W)^T$. (Difference is in the scale of coordinate of the embedding. $K = \wedge^{1/2}V$).
- LE: $K = L^{-1}$ or $K = (\lambda_{max}I L)$ and the result is also off in the scale of coordinate of the embedding as LLE.